Appendix B

The Fluxes and the Equations of Change

§B.1 NEWTON'S LAW OF VISCOSITY

$$[\boldsymbol{\tau} = -\mu(\nabla\mathbf{v} + (\nabla\mathbf{v})^\dagger) + (\tfrac{2}{3}\mu - \kappa)(\nabla\cdot\mathbf{v})\boldsymbol{\delta}]$$

Cartesian coordinates (x, y, z):

$$\tau_{xx} = -\mu\left[2\frac{\partial v_x}{\partial x}\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla\cdot\mathbf{v}) \qquad \text{(B.1-1)}^a$$

$$\tau_{yy} = -\mu\left[2\frac{\partial v_y}{\partial y}\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla\cdot\mathbf{v}) \qquad \text{(B.1-2)}^a$$

$$\tau_{zz} = -\mu\left[2\frac{\partial v_z}{\partial z}\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla\cdot\mathbf{v}) \qquad \text{(B.1-3)}^a$$

$$\tau_{xy} = \tau_{yx} = -\mu\left[\frac{\partial v_y}{\partial x} + \frac{\partial v_x}{\partial y}\right] \qquad \text{(B.1-4)}$$

$$\tau_{yz} = \tau_{zy} = -\mu\left[\frac{\partial v_z}{\partial y} + \frac{\partial v_y}{\partial z}\right] \qquad \text{(B.1-5)}$$

$$\tau_{zx} = \tau_{xz} = -\mu\left[\frac{\partial v_x}{\partial z} + \frac{\partial v_z}{\partial x}\right] \qquad \text{(B.1-6)}$$

in which

$$(\nabla\cdot\mathbf{v}) = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \qquad \text{(B.1-7)}$$

[a] When the fluid is assumed to have constant density, the term containing $(\nabla\cdot\mathbf{v})$ may be omitted. For monatomic gases at low density, the dilatational viscosity κ is zero.

§B.1 NEWTON'S LAW OF VISCOSITY (continued)

Cylindrical coordinates (r, θ, z):

$$\tau_{rr} = -\mu\left[2\frac{\partial v_r}{\partial r}\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla \cdot \mathbf{v}) \quad \text{(B.1-8)}^a$$

$$\tau_{\theta\theta} = -\mu\left[2\left(\frac{1}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r}\right)\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla \cdot \mathbf{v}) \quad \text{(B.1-9)}^a$$

$$\tau_{zz} = -\mu\left[2\frac{\partial v_z}{\partial z}\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla \cdot \mathbf{v}) \quad \text{(B.1-10)}^a$$

$$\tau_{r\theta} = \tau_{\theta r} = -\mu\left[r\frac{\partial}{\partial r}\left(\frac{v_\theta}{r}\right) + \frac{1}{r}\frac{\partial v_r}{\partial \theta}\right] \quad \text{(B.1-11)}$$

$$\tau_{\theta z} = \tau_{z\theta} = -\mu\left[\frac{1}{r}\frac{\partial v_z}{\partial \theta} + \frac{\partial v_\theta}{\partial z}\right] \quad \text{(B.1-12)}$$

$$\tau_{zr} = \tau_{rz} = -\mu\left[\frac{\partial v_r}{\partial z} + \frac{\partial v_z}{\partial r}\right] \quad \text{(B.1-13)}$$

in which

$$(\nabla \cdot \mathbf{v}) = \frac{1}{r}\frac{\partial}{\partial r}(rv_r) + \frac{1}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} \quad \text{(B.1-14)}$$

[a] When the fluid is assumed to have constant density, the term containing $(\nabla \cdot \mathbf{v})$ may be omitted. For monatomic gases at low density, the dilatational viscosity κ is zero.

Spherical coordinates (r, θ, ϕ):

$$\tau_{rr} = -\mu\left[2\frac{\partial v_r}{\partial r}\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla \cdot \mathbf{v}) \quad \text{(B.1-15)}^a$$

$$\tau_{\theta\theta} = -\mu\left[2\left(\frac{1}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r}\right)\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla \cdot \mathbf{v}) \quad \text{(B.1-16)}^a$$

$$\tau_{\phi\phi} = -\mu\left[2\left(\frac{1}{r\sin\theta}\frac{\partial v_\phi}{\partial \phi} + \frac{v_r + v_\theta\cot\theta}{r}\right)\right] + (\tfrac{2}{3}\mu - \kappa)(\nabla \cdot \mathbf{v}) \quad \text{(B.1-17)}^a$$

$$\tau_{r\theta} = \tau_{\theta r} = -\mu\left[r\frac{\partial}{\partial r}\left(\frac{v_\theta}{r}\right) + \frac{1}{r}\frac{\partial v_r}{\partial \theta}\right] \quad \text{(B.1-18)}$$

$$\tau_{\theta\phi} = \tau_{\phi\theta} = -\mu\left[\frac{\sin\theta}{r}\frac{\partial}{\partial \theta}\left(\frac{v_\phi}{\sin\theta}\right) + \frac{1}{r\sin\theta}\frac{\partial v_\theta}{\partial \phi}\right] \quad \text{(B.1-19)}$$

$$\tau_{\phi r} = \tau_{r\phi} = -\mu\left[\frac{1}{r\sin\theta}\frac{\partial v_r}{\partial \phi} + r\frac{\partial}{\partial r}\left(\frac{v_\phi}{r}\right)\right] \quad \text{(B.1-20)}$$

in which

$$(\nabla \cdot \mathbf{v}) = \frac{1}{r^2}\frac{\partial}{\partial r}(r^2 v_r) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \theta}(v_\theta \sin\theta) + \frac{1}{r\sin\theta}\frac{\partial v_\phi}{\partial \phi} \quad \text{(B.1-21)}$$

[a] When the fluid is assumed to have constant density, the term containing $(\nabla \cdot \mathbf{v})$ may be omitted. For monatomic gases at low density, the dilatational viscosity κ is zero.

§B.5 THE EQUATION OF MOTION IN TERMS OF τ

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + V\cdot\nabla$$

$$[\rho D\mathbf{v}/Dt = -\nabla p - [\nabla\cdot\boldsymbol{\tau}] + \rho\mathbf{g}]$$

Cartesian coordinates (x, y, z):[a]

$$\rho\left(\frac{\partial v_x}{\partial t} + v_x\frac{\partial v_x}{\partial x} + v_y\frac{\partial v_x}{\partial y} + v_z\frac{\partial v_x}{\partial z}\right) = -\frac{\partial p}{\partial x} - \left[\frac{\partial}{\partial x}\tau_{xx} + \frac{\partial}{\partial y}\tau_{yx} + \frac{\partial}{\partial z}\tau_{zx}\right] + \rho g_x \quad \text{(B.5-1)}$$

$$\rho\left(\frac{\partial v_y}{\partial t} + v_x\frac{\partial v_y}{\partial x} + v_y\frac{\partial v_y}{\partial y} + v_z\frac{\partial v_y}{\partial z}\right) = -\frac{\partial p}{\partial y} - \left[\frac{\partial}{\partial x}\tau_{xy} + \frac{\partial}{\partial y}\tau_{yy} + \frac{\partial}{\partial z}\tau_{zy}\right] + \rho g_y \quad \text{(B.5-2)}$$

$$\rho\left(\frac{\partial v_z}{\partial t} + v_x\frac{\partial v_z}{\partial x} + v_y\frac{\partial v_z}{\partial y} + v_z\frac{\partial v_z}{\partial z}\right) = -\frac{\partial p}{\partial z} - \left[\frac{\partial}{\partial x}\tau_{xz} + \frac{\partial}{\partial y}\tau_{yz} + \frac{\partial}{\partial z}\tau_{zz}\right] + \rho g_z \quad \text{(B.5-3)}$$

[a] These equations have been written without making the assumption that $\boldsymbol{\tau}$ is symmetric. This means, for example, that when the usual assumption is made that the stress tensor is symmetric, τ_{xy} and τ_{yx} may be interchanged.

Cylindrical coordinates (r, θ, z):[b]

$$\rho\left(\frac{\partial v_r}{\partial t} + v_r\frac{\partial v_r}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_r}{\partial \theta} + v_z\frac{\partial v_r}{\partial z} - \frac{v_\theta^2}{r}\right) = -\frac{\partial p}{\partial r} - \left[\frac{1}{r}\frac{\partial}{\partial r}(r\tau_{rr}) + \frac{1}{r}\frac{\partial}{\partial \theta}\tau_{\theta r} + \frac{\partial}{\partial z}\tau_{zr} - \frac{\tau_{\theta\theta}}{r}\right] + \rho g_r \quad \text{(B.5-4)}$$

$$\rho\left(\frac{\partial v_\theta}{\partial t} + v_r\frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\theta}{\partial \theta} + v_z\frac{\partial v_\theta}{\partial z} + \frac{v_r v_\theta}{r}\right) = -\frac{1}{r}\frac{\partial p}{\partial \theta} - \left[\frac{1}{r^2}\frac{\partial}{\partial r}(r^2\tau_{r\theta}) + \frac{1}{r}\frac{\partial}{\partial \theta}\tau_{\theta\theta} + \frac{\partial}{\partial z}\tau_{z\theta} + \frac{\tau_{\theta r} - \tau_{r\theta}}{r}\right] + \rho g_\theta \quad \text{(B.5-5)}$$

$$\rho\left(\frac{\partial v_z}{\partial t} + v_r\frac{\partial v_z}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_z}{\partial \theta} + v_z\frac{\partial v_z}{\partial z}\right) = -\frac{\partial p}{\partial z} - \left[\frac{1}{r}\frac{\partial}{\partial r}(r\tau_{rz}) + \frac{1}{r}\frac{\partial}{\partial \theta}\tau_{\theta z} + \frac{\partial}{\partial z}\tau_{zz}\right] + \rho g_z \quad \text{(B.5-6)}$$

[b] These equations have been written without making the assumption that $\boldsymbol{\tau}$ is symmetric. This means, for example, that when the usual assumption is made that the stress tensor is symmetric, $\tau_{r\theta} - \tau_{\theta r} = 0$.

Spherical coordinates (r, θ, ϕ):[c]

$$\rho\left(\frac{\partial v_r}{\partial t} + v_r\frac{\partial v_r}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r\sin\theta}\frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r}\right) = -\frac{\partial p}{\partial r}$$
$$- \left[\frac{1}{r^2}\frac{\partial}{\partial r}(r^2\tau_{rr}) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \theta}(\tau_{\theta r}\sin\theta) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \phi}\tau_{\phi r} - \frac{\tau_{\theta\theta} + \tau_{\phi\phi}}{r}\right] + \rho g_r \quad \text{(B.5-7)}$$

$$\rho\left(\frac{\partial v_\theta}{\partial t} + v_r\frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r\sin\theta}\frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2\cot\theta}{r}\right) = -\frac{1}{r}\frac{\partial p}{\partial \theta}$$
$$- \left[\frac{1}{r^3}\frac{\partial}{\partial r}(r^3\tau_{r\theta}) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \theta}(\tau_{\theta\theta}\sin\theta) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \phi}\tau_{\phi\theta} + \frac{(\tau_{\theta r} - \tau_{r\theta}) - \tau_{\phi\phi}\cot\theta}{r}\right) + \rho g_\theta \quad \text{(B.5-8)}$$

$$\rho\left(\frac{\partial v_\phi}{\partial t} + v_r\frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r\sin\theta}\frac{\partial v_\phi}{\partial \phi} + \frac{v_\phi v_r + v_\theta v_\phi\cot\theta}{r}\right) = -\frac{1}{r\sin\theta}\frac{\partial p}{\partial \phi}$$
$$- \left[\frac{1}{r^3}\frac{\partial}{\partial r}(r^3\tau_{r\phi}) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \theta}(\tau_{\theta\phi}\sin\theta) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \phi}\tau_{\phi\phi} + \frac{(\tau_{\phi r} - \tau_{r\phi}) + \tau_{\phi\theta}\cot\theta}{r}\right] + \rho g_\phi \quad \text{(B.5-9)}$$

[c] These equations have been written without making the assumption that $\boldsymbol{\tau}$ is symmetric. This means, for example, that when the usual assumption is made that the stress tensor is symmetric, $\tau_{r\theta} - \tau_{\theta r} = 0$.

$$\frac{\partial}{\partial t}(\rho\vec{v}) = -\nabla\cdot\rho\vec{v}\vec{v} - \nabla P - \nabla\cdot\underline{\underline{\tau}} + \rho\vec{g}$$

$$\frac{\partial}{\partial t}(\rho v_i) = -\frac{\partial}{\partial x_j}(\rho v_j v_i) - \frac{\partial}{\partial x_j}P - \frac{\partial}{\partial x_j}\tau_{ji} + \rho g_i \qquad i\text{-Dir.}$$

$$\rightarrow \frac{\partial}{\partial t}(\rho u) = -\frac{\partial}{\partial x}(\rho uu) - \frac{\partial}{\partial y}(\rho vu) - \frac{\partial}{\partial z}(\rho wu) - \frac{\partial}{\partial x}P - \frac{\partial}{\partial x}\tau_{xx} - \frac{\partial}{\partial y}\tau_{yx} - \frac{\partial}{\partial z}\tau_{zx} + \rho g_x$$

§B.6 EQUATION OF MOTION FOR A NEWTONIAN FLUID WITH CONSTANT ρ AND μ

$$[\rho D\mathbf{v}/Dt = -\nabla p + \mu\nabla^2\mathbf{v} + \rho\mathbf{g}]$$

Cartesian coordinates (x, y, z):

$$\rho\left(\frac{\partial v_x}{\partial t} + v_x\frac{\partial v_x}{\partial x} + v_y\frac{\partial v_x}{\partial y} + v_z\frac{\partial v_x}{\partial z}\right) = -\frac{\partial p}{\partial x} + \mu\left[\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2}\right] + \rho g_x \tag{B.6-1}$$

$$\rho\left(\frac{\partial v_y}{\partial t} + v_x\frac{\partial v_y}{\partial x} + v_y\frac{\partial v_y}{\partial y} + v_z\frac{\partial v_y}{\partial z}\right) = -\frac{\partial p}{\partial y} + \mu\left[\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2}\right] + \rho g_y \tag{B.6-2}$$

$$\rho\left(\frac{\partial v_z}{\partial t} + v_x\frac{\partial v_z}{\partial x} + v_y\frac{\partial v_z}{\partial y} + v_z\frac{\partial v_z}{\partial z}\right) = -\frac{\partial p}{\partial z} + \mu\left[\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2}\right] + \rho g_z \tag{B.6-3}$$

Cylindrical coordinates (r, θ, z):

$$\rho\left(\frac{\partial v_r}{\partial t} + v_r\frac{\partial v_r}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_r}{\partial \theta} + v_z\frac{\partial v_r}{\partial z} - \frac{v_\theta^2}{r}\right) = -\frac{\partial p}{\partial r} + \mu\left[\frac{\partial}{\partial r}\left(\frac{1}{r}\frac{\partial}{\partial r}(rv_r)\right) + \frac{1}{r^2}\frac{\partial^2 v_r}{\partial \theta^2} + \frac{\partial^2 v_r}{\partial z^2} - \frac{2}{r^2}\frac{\partial v_\theta}{\partial \theta}\right] + \rho g_r \tag{B.6-4}$$

$$\rho\left(\frac{\partial v_\theta}{\partial t} + v_r\frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\theta}{\partial \theta} + v_z\frac{\partial v_\theta}{\partial z} + \frac{v_r v_\theta}{r}\right) = -\frac{1}{r}\frac{\partial p}{\partial \theta} + \mu\left[\frac{\partial}{\partial r}\left(\frac{1}{r}\frac{\partial}{\partial r}(rv_\theta)\right) + \frac{1}{r^2}\frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{\partial^2 v_\theta}{\partial z^2} + \frac{2}{r^2}\frac{\partial v_r}{\partial \theta}\right] + \rho g_\theta \tag{B.6-5}$$

$$\rho\left(\frac{\partial v_z}{\partial t} + v_r\frac{\partial v_z}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_z}{\partial \theta} + v_z\frac{\partial v_z}{\partial z}\right) = -\frac{\partial p}{\partial z} + \mu\left[\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial v_z}{\partial r}\right) + \frac{1}{r^2}\frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2}\right] + \rho g_z \tag{B.6-6}$$

Spherical coordinates (r, θ, ϕ):

$$\rho\left(\frac{\partial v_r}{\partial t} + v_r\frac{\partial v_r}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r\sin\theta}\frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r}\right) = -\frac{\partial p}{\partial r}$$
$$+ \mu\left[\frac{1}{r^2}\frac{\partial^2}{\partial r^2}(r^2 v_r) + \frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(\sin\theta\frac{\partial v_r}{\partial \theta}\right) + \frac{1}{r^2\sin^2\theta}\frac{\partial^2 v_r}{\partial \phi^2}\right] + \rho g_r \tag{B.6-7}$$ [a]

$$\rho\left(\frac{\partial v_\theta}{\partial t} + v_r\frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r\sin\theta}\frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2\cot\theta}{r}\right) = -\frac{1}{r}\frac{\partial p}{\partial \theta}$$
$$+ \mu\left[\frac{1}{r^2}\frac{\partial}{\partial r}\left(r^2\frac{\partial v_\theta}{\partial r}\right) + \frac{1}{r^2}\frac{\partial}{\partial \theta}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial \theta}(v_\theta\sin\theta)\right) + \frac{1}{r^2\sin^2\theta}\frac{\partial^2 v_\theta}{\partial \phi^2} + \frac{2}{r^2}\frac{\partial v_r}{\partial \theta} - \frac{2\cot\theta}{r^2\sin\theta}\frac{\partial v_\phi}{\partial \phi}\right] + \rho g_\theta \tag{B.6-8}$$

$$\rho\left(\frac{\partial v_\phi}{\partial t} + v_r\frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r\sin\theta}\frac{\partial v_\phi}{\partial \phi} + \frac{v_\phi v_r + v_\theta v_\phi\cot\theta}{r}\right) = -\frac{1}{r\sin\theta}\frac{\partial p}{\partial \phi}$$
$$+ \mu\left[\frac{1}{r^2}\frac{\partial}{\partial r}\left(r^2\frac{\partial v_\phi}{\partial r}\right) + \frac{1}{r^2}\frac{\partial}{\partial \theta}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial \theta}(v_\phi\sin\theta)\right) + \frac{1}{r^2\sin^2\theta}\frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2\sin\theta}\frac{\partial v_r}{\partial \phi} + \frac{2\cot\theta}{r^2\sin\theta}\frac{\partial v_\theta}{\partial \phi}\right] + \rho g_\theta \tag{B.6-9}$$

[a] The quantity in the brackets in Eq. B.6-7 is *not* what one would expect from Eq. (M) for $[\nabla \cdot \nabla\mathbf{v}]$ in Table A.7-3, because we have added to Eq. (M) the expression for $(2/r)(\nabla \cdot \mathbf{v})$, which is zero for fluids with constant ρ. This gives a much simpler equation.

§B.3 FICK'S (FIRST) LAW OF BINARY DIFFUSION[a]

$$[\mathbf{j}_A = -\rho\mathscr{D}_{AB}\nabla\omega_A]$$

Cartesian coordinates (x, y, z):

$$j_{Ax} = -\rho\mathscr{D}_{AB}\frac{\partial\omega_A}{\partial x} \tag{B.3-1}$$

$$j_{Ay} = -\rho\mathscr{D}_{AB}\frac{\partial\omega_A}{\partial y} \tag{B.3-2}$$

$$j_{Az} = -\rho\mathscr{D}_{AB}\frac{\partial\omega_A}{\partial z} \tag{B.3-3}$$

Cylindrical coordinates (r, θ, z):

$$j_{Ar} = -\rho\mathscr{D}_{AB}\frac{\partial\omega_A}{\partial r} \tag{B.3-4}$$

$$j_{A\theta} = -\rho\mathscr{D}_{AB}\frac{1}{r}\frac{\partial\omega_A}{\partial \theta} \tag{B.3-5}$$

$$j_{Az} = -\rho\mathscr{D}_{AB}\frac{\partial\omega_A}{\partial z} \tag{B.3-6}$$

Spherical coordinates (r, θ, ϕ):

$$j_{Ar} = -\rho\mathscr{D}_{AB}\frac{\partial\omega_A}{\partial r} \tag{B.3-7}$$

$$j_{A\theta} = -\rho\mathscr{D}_{AB}\frac{1}{r}\frac{\partial\omega_A}{\partial \theta} \tag{B.3-8}$$

$$j_{A\phi} = -\rho\mathscr{D}_{AB}\frac{1}{r\sin\theta}\frac{\partial\omega_A}{\partial \phi} \tag{B.3-9}$$

[a] To get the molar fluxes with respect to the molar average velocity, replace $\mathbf{j}_A$, ρ, and ω_A by $\mathbf{J}_A^*$, c, and x_A.

§B.4 THE EQUATION OF CONTINUITY[a]

$$[\partial\rho/\partial t + (\nabla\cdot\rho\mathbf{v}) = 0]$$

Cartesian coordinates (x, y, z):

$$\frac{\partial\rho}{\partial t} + \frac{\partial}{\partial x}(\rho v_x) + \frac{\partial}{\partial y}(\rho v_y) + \frac{\partial}{\partial z}(\rho v_z) = 0 \tag{B.4-1}$$

Cylindrical coordinates (r, θ, z):

$$\frac{\partial\rho}{\partial t} + \frac{1}{r}\frac{\partial}{\partial r}(\rho r v_r) + \frac{1}{r}\frac{\partial}{\partial \theta}(\rho v_\theta) + \frac{\partial}{\partial z}(\rho v_z) = 0 \tag{B.4-2}$$

Spherical coordinates (r, θ, ϕ):

$$\frac{\partial\rho}{\partial t} + \frac{1}{r^2}\frac{\partial}{\partial r}(\rho r^2 v_r) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \theta}(\rho v_\theta \sin\theta) + \frac{1}{r\sin\theta}\frac{\partial}{\partial \phi}(\rho v_\phi) = 0 \tag{B.4-3}$$

[a] When the fluid is assumed to have constant mass density ρ, the equation simplifies to $(\nabla\cdot\mathbf{v}) = 0$.